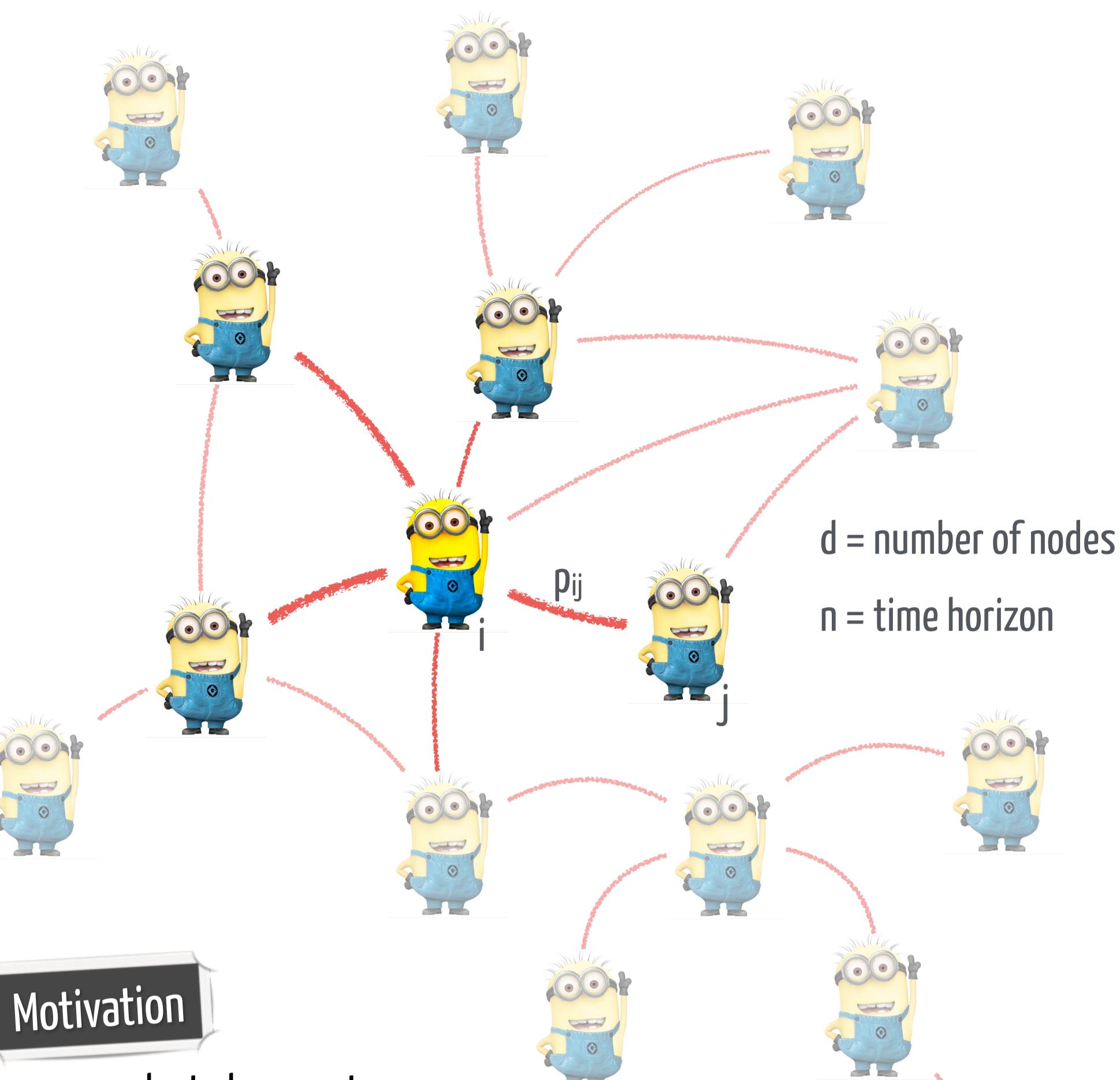


# Revealing graph bandits for maximizing local influence

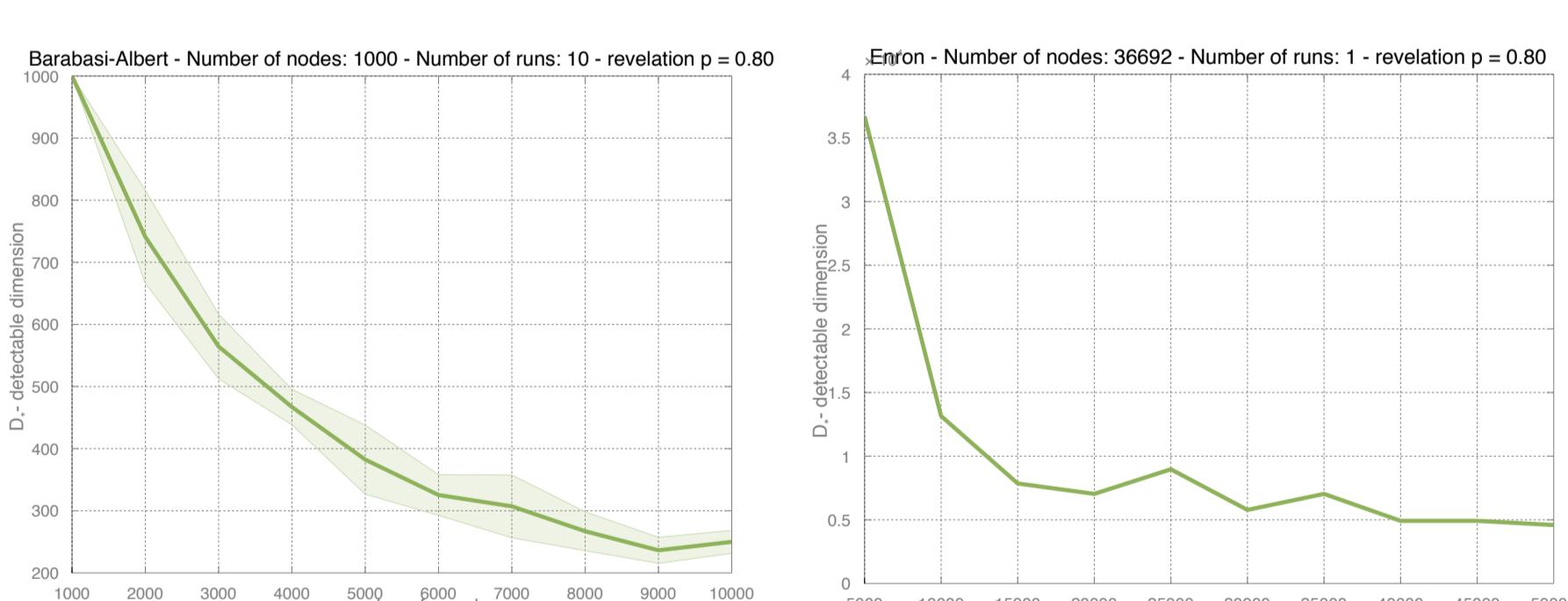


## Detectable dimension

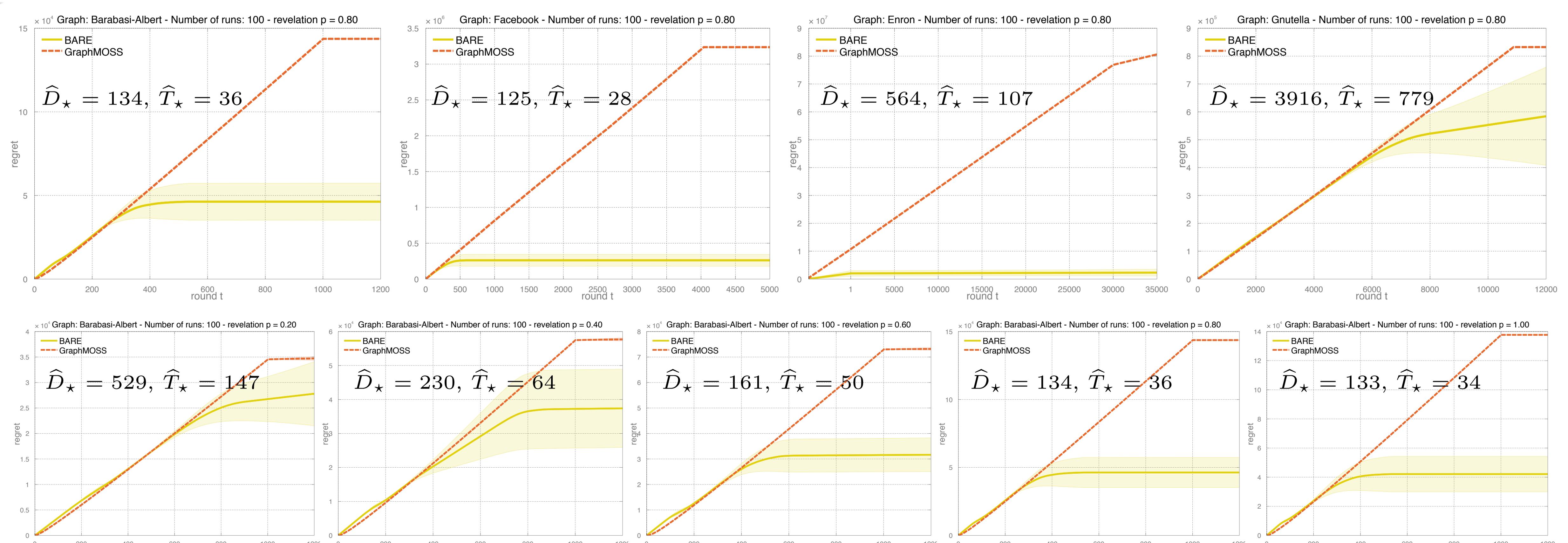
- number of nodes we can efficiently extract in less than n rounds
- function D controls number of nodes given a gap  
 $D(\Delta) \stackrel{\text{def}}{=} |\{i \leq d : r_i^* - r_i^\circ \leq \Delta\}|$
- $D(r) = d$  for  $r \geq r^*$  and  $D(0) = \text{number of most influenced nodes}$
- **Detectable dimension  $D^*$**  =  $D(\Delta^*)$
- Detectable gap  $\Delta^*$  constants coming from the analysis and the Bernstein inequality

$$\Delta^* \stackrel{\text{def}}{=} 16 \sqrt{\frac{r^* d \log(nd)}{T^*}} + \frac{80 d \log(nd)}{T^*}$$

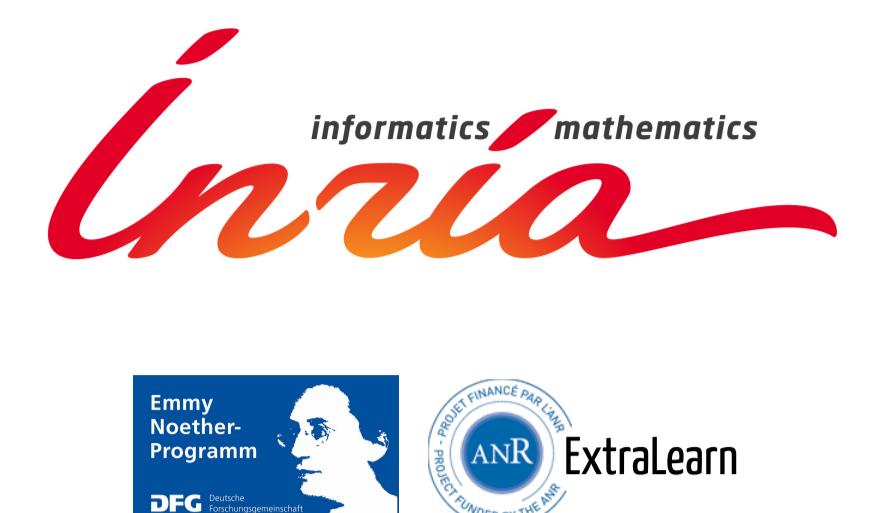
- Detectable horizon  $T^*$ , smallest integer s.t.  $T^* r^* \geq \sqrt{D^* n r^*}$
  - Equivalently:  $D^*$  corresponding to smallest  $T^*$  such that
- $$T^* r^* \geq \sqrt{D \left( 16 \sqrt{\frac{r^* d \log(nd)}{T^*}} + \frac{80 d \log(nd)}{T^*} \right) n r^*}$$
- For (easy, structured) star graphs  $D^* = 1$  even for small n (**big gain**)
  - For (difficult) empty graphs  $D^* = d$  even for large n (**no gain**)
  - In general:  $D^*$  roughly decreases with n and it is **small when D decreases quickly**
  - For n large enough  $D^*$  is the number of the most influences nodes
  - Example:  $D^*$  for Barabási-Albert model & Enron graph as a function of n



## Experiments



ALEXANDRA CARPENTIER and MICHAL VALKO  
carpentier@math.uni-potsdam.de and michal.valko@inria.fr



## Setting

**Unknown**  $(p_{ij})_{ij}$  — (symmetric) probability of influences

In each time step  $t = 1, \dots, n$

learner picks a node  $k_t$

environment **reveals** the set of influenced node  $S_{k,t}$

**Select influential people** = Find the strategy maximising

$$L_n = \sum_{t=1}^n |S_{k_t, t}|$$



## Our solution

**BAndit REvelator**: 2-phase algorithm

- **global exploration phase**

- super-efficient exploration 😊
- linear regret 😤 — needs to be short!
- extracts  $D^*$  nodes

- **bandit phase**

- uses a minimax-optimal bandit algorithm
- GraphMOSS is a little brother of MOSS
- has a "square root" regret on  $D^*$  nodes
- **$D^*$  realizes the optimal trade-off!**
- different from exploration/exploitation tradeoff

## Definitions

The number of expected influences of node  $k$  is by definition

$$r_k = \mathbb{E}[|S_{k,t}|] = \sum_{j \leq d} p_{kj}$$

Oracle strategy always selects the best

$$k^* = \arg \max_k \mathbb{E} \left[ \sum_{t=1}^n |S_{k,t}| \right] = \arg \max_k nr_k$$

Expected regret of the oracle strategy

$$\mathbb{E}[L_n^*] = nr^*$$

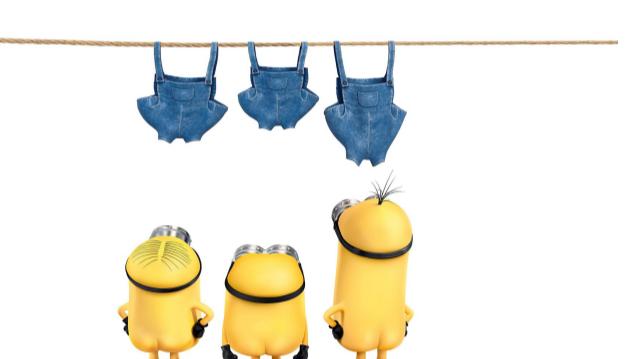
Expected regret of any adaptive strategy unaware of  $(p_{ij})_{ij}$

$$\mathbb{E}[R_n] = \mathbb{E}[L_n^*] - \mathbb{E}[L_n]$$

## Baseline

- We **only receive**  $|S|$  instead of  $S$

- Can be mapped to **multi-arm bandits**



- rewards are 0, ..., d
- variance bounded with  $r_{kt}$

- We adapt MOSS to **GraphMOSS**

- Regret upper bound of GraphMOSS

$$\mathbb{E}[R_n] \leq U \min(r^* n, r^* d + \sqrt{r^* n d})$$

- matching lower bound

## Guarantees

Upper bound on the regret of BARE

$$\mathbb{E}[R_n] \leq C \min(r^* n, D^* r^* + \sqrt{r^* n D^*})$$

Matching lower bound

## Algorithm

### GraphMOSS

**Input**

$d$ : the number of nodes

$n$ : time horizon

**Initialization**

Sample each arm twice

Update  $\hat{r}_{k,2d}, \hat{\sigma}_{k,2d}$ , and  $T_{k,2d} \leftarrow 2$ , for  $\forall k \leq d$

for  $t = 2d+1, \dots, n$  do

$$C_{k,t} \leftarrow 2\hat{\sigma}_{k,t} \sqrt{\frac{\max(\log(n/(dT_{k,t})), 0)}{T_{k,t}}} + \frac{2\max(\log(n/(dT_{k,t})), 0)}{T_{k,t}}, \text{ for } \forall k \leq d$$

$$k_t \leftarrow \arg \max_k \hat{r}_{k,t} + C_{k,t}$$

Sample node  $k_t$  and receive  $|S_{k_t, t}|$

Update  $\hat{r}_{k,t+1}, \hat{\sigma}_{k,t+1}$ , and  $T_{k,t+1}$ , for  $\forall k \leq d$

end for



## Algorithm

### BARE-BAndit REvelator

**Input**

$d$ : the number of nodes

$n$ : time horizon



**Initialization**

$T_{k,t} \leftarrow 0$ , for  $\forall k \leq d$

$\hat{r}_{k,t}^\circ \leftarrow 0$ , for  $\forall k \leq d$

$t \leftarrow 1$ ,  $\hat{T}_* \leftarrow 0$ ,  $\hat{D}_{*,t} \leftarrow d$ ,  $\hat{\sigma}_{*,1} \leftarrow d$

**Global exploration phase**

while  $t (\hat{\sigma}_{*,t} - 4\sqrt{d \log(dn)/t}) \leq \sqrt{\hat{D}_{*,tn}}$  do

Influence a node at random (choose  $k_t$  uniformly at random) and get  $S_{k_t, t}$  from this node

$$\hat{r}_{k,t+1} \leftarrow \frac{t}{t+1} \hat{r}_{k,t}^\circ + \frac{t}{t+1} S_{k_t, t}(k)$$

$$\hat{\sigma}_{*,t+1} \leftarrow \max_{k'} \sqrt{\hat{r}_{k',t+1}^\circ + 8d \log(nd)/(t+1)}$$

$$w_{*,t+1} \leftarrow 8\hat{\sigma}_{*,t+1} \sqrt{\frac{d \log(nd)}{t+1}} + \frac{24d \log(nd)}{t+1}$$

$$\hat{D}_{*,t+1} \leftarrow \left\{ k : \max_{k'} \hat{r}_{k',t+1}^\circ - \hat{r}_{k,t+1}^\circ \leq w_{*,t+1} \right\}$$

**end while**

$\hat{T}_* \leftarrow t$

**Bandit phase**

Run minimax-optimal bandit algorithm on the  $\hat{D}_{*,\hat{T}_*}$  chosen nodes (e.g., Algorithm 1)