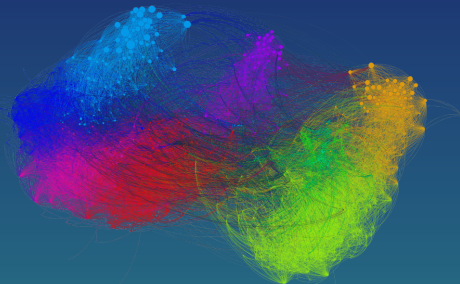


Graphs in Machine Learning

Michal Valko

Inria Lille - Nord Europe, France

Partially based on material by: Branislav Kveton,
Partha Niyogi, Rob Fergus



Last Lecture

- ▶ Inductive and transductive semi-supervised learning
- ▶ Manifold regularization
- ▶ Theory of Laplacian-based manifold methods
- ▶ Transductive learning stability based bounds
- ▶ Online Semi-Supervised Learning
- ▶ Online incremental k -centers

This Lecture

- ▶ Examples of applications of online SSL
- ▶ Analysis of online SSL
- ▶ SSL Learnability
- ▶ When does graph-based SSL provably help?
- ▶ Scaling harmonic functions to millions of samples

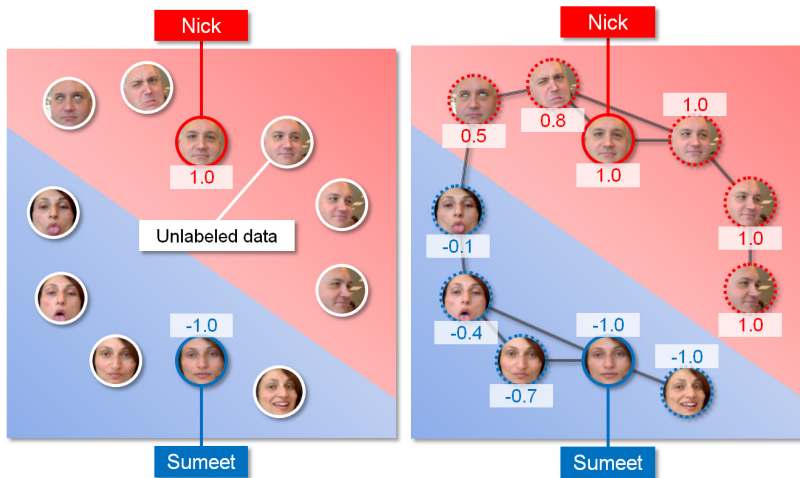
Next Lab Session

- ▶ 16. 11. 2015 by Daniele.Calandriello@inria.fr
- ▶ Content
 - ▶ Semi-supervised learning
 - ▶ Graph quantization
 - ▶ Online face recognizer
- ▶ AR: record a video with faces
- ▶ Short written report
- ▶ Questions to piazza
- ▶ *Deadline: 30. 11. 2015*
- ▶ http://researchers.lille.inria.fr/~calandri/ta/graphs/td2_handout.pdf

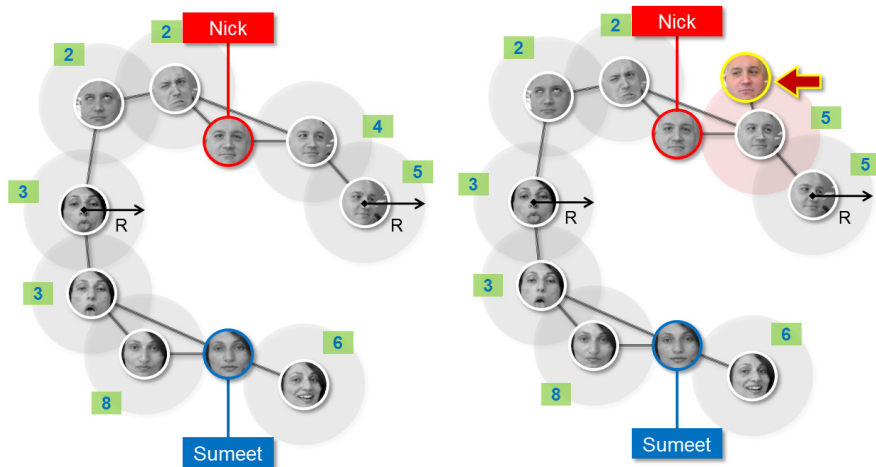
Final Class projects

- ▶ detailed description on the class website
- ▶ preferred option: you come up with the topic
- ▶ theory/implementation/review or a combination
- ▶ one or two people per project (exceptionally three)
- ▶ grade 60%: report + short presentation of the **team**
- ▶ deadlines
 - ▶ 23. 11. 2015 - strongly recommended DL for taking projects
 - ▶ 30. 11. 2015 - hard DL for taking projects
 - ▶ 06. 01. 2016 - submission of the project report
 - ▶ 11. 01. 2016 (TBC) or later - project presentation
- ▶ list of suggested topics on piazza

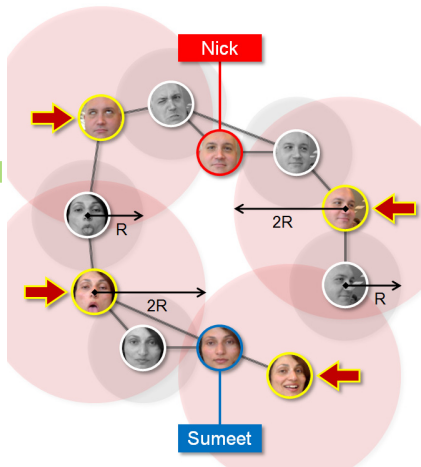
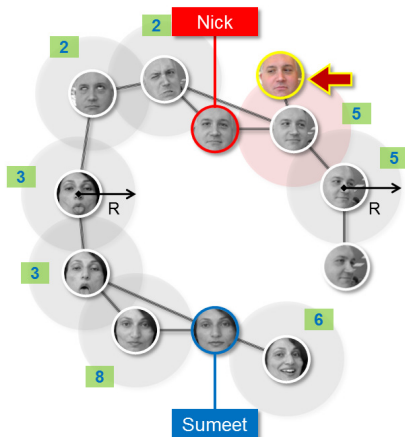
Where we left off: Online SSL with Graphs



Where we left off: Online SSL with Graphs



Where we left off: Online SSL with Graphs



Where we left off: Online SSL with Graphs

Video examples

<http://www.bkveton.com/videos/Coffee.mp4>

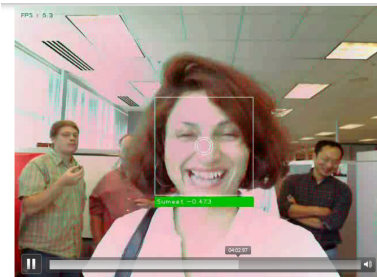
<http://www.bkveton.com/videos/Ad.mp4>

[http://researchers.lille.inria.fr/~valko/hp/serve.php?
what=publications/kveton2009nipsdemo.adaptation.mov](http://researchers.lille.inria.fr/~valko/hp/serve.php?what=publications/kveton2009nipsdemo.adaptation.mov)

[http://researchers.lille.inria.fr/~valko/hp/serve.php?
what=publications/kveton2009nipsdemo.officespace.mov](http://researchers.lille.inria.fr/~valko/hp/serve.php?what=publications/kveton2009nipsdemo.officespace.mov)

<http://bcove.me/a2derjeh>

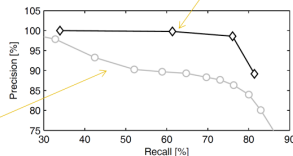
SSL with Graphs: Some experimental results



- 8 people classification
- Making funny faces
- 4 faces/person are labeled

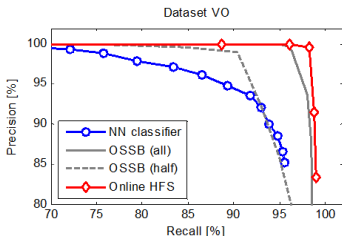
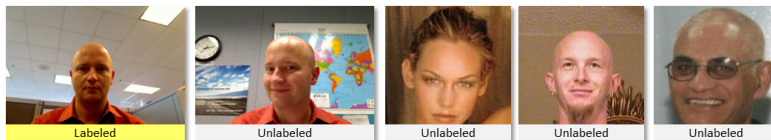
Nearest Neighbor

Our method

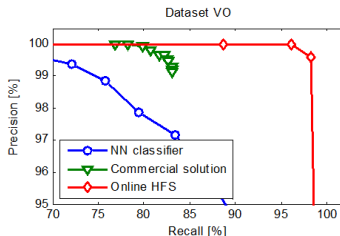


SSL with Graphs: Some experimental results

- One person moves among various indoor locations
- 4 labeled examples of a person in the cubicle



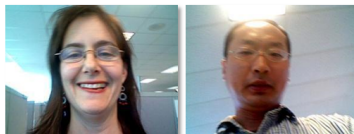
Online HFS outperforms OSSB (even when the weak learners are chosen using future data)



Online HFS yields better results than a commercial solution at 20% of the computational cost

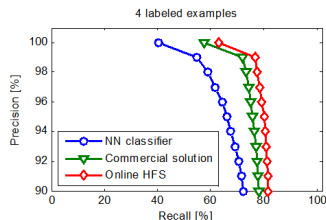
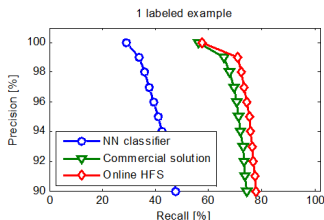
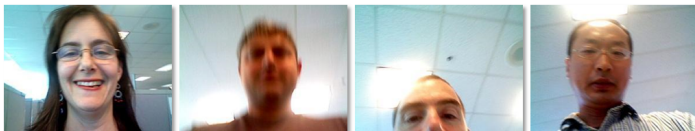
SSL with Graphs: Some experimental results

- **Logging in** with faces instead of password
- Able to **learn** and improve



SSL with Graphs: Some experimental results

- 16 people log twice into a tablet PC at 10 locations



Online HFS yields better results than a commercial solution at 20% of the computational cost

Online SSL with Graphs: Analysis

What can we guarantee?

Three sources of error

- ▶ generalization error — if all data: $(\ell_t^* - y_t)^2$
- ▶ online error — data only incrementally: $(\ell_t^o[t] - \ell_t^*)^2$
- ▶ quantization error — memory limitation: $(\ell_t^q[t] - \ell_t^o[t])^2$

All together:

$$\frac{1}{n} \sum_{t=1}^n (\ell_t^q[t] - y_t)^2 \leq \frac{9}{2n} \sum_{t=1}^n (\ell_t^* - y_t)^2 + \frac{9}{2n} \sum_{t=1}^n (\ell_t^o[t] - \ell_t^*)^2 + \frac{9}{2n} \sum_{t=1}^n (\ell_t^q[t] - \ell_t^o[t])^2$$

Since for any $a, b, c, d \in [-1, 1]$:

$$(a - b)^2 \leq \frac{9}{2} [(a - c)^2 + (c - d)^2 + (d - b)^2]$$

Online SSL with Graphs: Analysis

Bounding **transduction error** $(\ell_t^* - y_t)^2$

If all labeled examples I are i.i.d., $c_l = 1$ and $c_l \gg c_u$, then

$$R(\ell^*) \leq \hat{R}(\ell^*) + \underbrace{\beta + \sqrt{\frac{2 \ln(2/\delta)}{n_l}} (n_l \beta + 4)}_{\text{transductive error } \Delta_T(\beta, n_l, \delta)}$$
$$\beta \leq 2 \left[\frac{\sqrt{2}}{\gamma_g + 1} + \sqrt{2n_l} \frac{1 - c_u}{c_u} \frac{\lambda_M(\mathbf{L}) + \gamma_g}{\gamma_g^2 + 1} \right]$$

holds with the probability of $1 - \delta$, where

$$R(\ell^*) = \frac{1}{n} \sum_t (\ell_t^* - y_t)^2 \quad \text{and} \quad \hat{R}(\ell^*) = \frac{1}{n_l} \sum_{t \in I} (\ell_t^* - y_t)^2$$

How should we set γ_g ?

Online SSL with Graphs: Analysis

Bounding online error $(\ell_t^o[t] - \ell_t^*)^2$

Idea: If \mathbf{L} and \mathbf{L}^o are regularized, then HFSs get closer together.

since they get closer to zero

Recall $\ell = (\mathbf{C}^{-1}\mathbf{Q} + \mathbf{I})^{-1}\mathbf{y}$, where $\mathbf{Q} = \mathbf{L} + \gamma_g \mathbf{I}$

and also $\mathbf{v} \in \mathbb{R}^{n \times 1}$, $\lambda_m(A) \|\mathbf{v}\|_2 \leq \|A\mathbf{v}\|_2 \leq \lambda_M(A) \|\mathbf{v}\|_2$

$$\|\ell\|_2 \leq \frac{\|\mathbf{y}\|_2}{\lambda_m(\mathbf{C}^{-1}\mathbf{Q} + \mathbf{I})} = \frac{\|\mathbf{y}\|_2}{\frac{\lambda_m(\mathbf{Q})}{\lambda_M(\mathbf{C})} + 1} \leq \frac{\sqrt{n_I}}{\gamma_g + 1}$$

Difference between offline and online solutions:

$$(\ell_t^o[t] - \ell_t^*)^2 \leq \|\ell^o[t] - \ell^*\|_\infty^2 \leq \|\ell^o[t] - \ell^*\|_2^2 \leq \left(\frac{2\sqrt{n_I}}{\gamma_g + 1} \right)^2$$

Again, how should we set γ_g ?

Online SSL with Graphs: Analysis

Bounding **quantization error** $(\ell_t^q[t] - \ell_t^o[t])^2$

How are the quantized and full solution different?

$$\ell^* = \min_{\ell \in \mathbb{R}^n} (\ell - \mathbf{y})^\top \mathbf{C} (\ell - \mathbf{y}) + \ell^\top \mathbf{Q} \ell$$

In Q! \mathbf{Q}^o (online) vs. \mathbf{Q}^q (quantized)

We have: $\ell^o = (\mathbf{C}^{-1} \mathbf{Q}^o + \mathbf{I})^{-1} \mathbf{y}$ vs. $\ell^q = (\mathbf{C}^{-1} \mathbf{Q}^q + \mathbf{I})^{-1} \mathbf{y}$

Let $\mathbf{Z}^q = \mathbf{C}^{-1} \mathbf{Q}^q + \mathbf{I}$ and $\mathbf{Z}^o = \mathbf{C}^{-1} \mathbf{Q}^o + \mathbf{I}$.

$$\begin{aligned} \ell^q - \ell^o &= (\mathbf{Z}^q)^{-1} \mathbf{y} - (\mathbf{Z}^o)^{-1} \mathbf{y} = (\mathbf{Z}^q \mathbf{Z}^o)^{-1} (\mathbf{Z}^o - \mathbf{Z}^q) \mathbf{y} \\ &= (\mathbf{Z}^q \mathbf{Z}^o)^{-1} \mathbf{C}^{-1} (\mathbf{Q}^o - \mathbf{Q}^q) \mathbf{y} \end{aligned}$$

Online SSL with Graphs: Analysis

Bounding **quantization error** $(\ell_t^q[t] - \ell_t^o[t])^2$

$$\begin{aligned}\ell^q - \ell^o &= (\mathbf{Z}^q)^{-1}\mathbf{y} - (\mathbf{Z}^o)^{-1}\mathbf{y} = (\mathbf{Z}^q\mathbf{Z}^o)^{-1}(\mathbf{Z}^o - \mathbf{Z}^q)\mathbf{y} \\ &= (\mathbf{Z}^q\mathbf{Z}^o)^{-1}\mathbf{C}^{-1}(\mathbf{Q}^o - \mathbf{Q}^q)\mathbf{y}\end{aligned}$$

$$\|\ell^q - \ell^o\|_2 \leq \frac{\lambda_M(\mathbf{C}^{-1})\|(\mathbf{Q}^q - \mathbf{Q}^o)\mathbf{y}\|_2}{\lambda_m(\mathbf{Z}^q)\lambda_m(\mathbf{Z}^o)}$$

$\|\cdot\|_F$ and $\|\cdot\|_2$ are compatible and y_i is zero when unlabeled:

$$\|(\mathbf{Q}^q - \mathbf{Q}^o)\mathbf{y}\|_2 \leq \|\mathbf{Q}^q - \mathbf{Q}^o\|_F \cdot \|\mathbf{y}\|_2 \leq \sqrt{n_I}\|\mathbf{Q}^q - \mathbf{Q}^o\|_F$$

Furthermore, $\lambda_m(\mathbf{Z}^o) \geq \frac{\lambda_m(\mathbf{Q}^o)}{\lambda_M(\mathbf{C})} + 1 \geq \gamma_g$ and $\lambda_M(\mathbf{C}^{-1}) \leq c_u^{-1}$

$$\text{We get } \|\ell^q - \ell^o\|_2 \leq \frac{\sqrt{n_I}}{c_u\gamma_g^2} \|\mathbf{Q}^q - \mathbf{Q}^o\|_F$$

Online SSL with Graphs: Analysis

Bounding quantization error $(\ell_t^q[t] - \ell_t^o[t])^2$

The quantization error depends on $\|\mathbf{Q}^q - \mathbf{Q}^o\|_F = \|\mathbf{L}^q - \mathbf{L}^o\|_F$.

When can we keep $\|\mathbf{L}^q - \mathbf{L}^o\|_F$ under control?

Charikar guarantees **distortion** error of at most $Rm/(m-1)$

For what kind of data $\{\mathbf{x}_i\}_{i=1,\dots,n}$ is the distortion small?

Assume manifold \mathcal{M}

- ▶ all $\{\mathbf{x}_i\}_{i \geq 1}$ lie on a smooth s -dimensional compact \mathcal{M}
- ▶ with boundary of bounded geometry Def. 11 of Hein [HAL07]
 - ▶ should not intersect itself
 - ▶ should not fold back onto itself
 - ▶ has finite volume V
 - ▶ has finite surface area A

Online SSL with Graphs: Analysis

Bounding **quantization error** $(\ell_t^q[t] - \ell_t^o[t])^2$

Bounding $\|\mathbf{L}^q - \mathbf{L}^o\|_F$ when $\mathbf{x}_i \in \mathcal{M}$

Consider k -sphere packing of radius r with centers contained in \mathcal{M} .

What is the maximum volume of this packing?

$kc_s r^s \leq V + Ac_{\mathcal{M}}r$ with $c_s, c_{\mathcal{M}}$ depending on dimension and \mathcal{M} .

If k is large $\rightarrow r < \text{injectivity radius}$ of \mathcal{M} [HAL07] and $r < 1$:

$$r < ((V + Ac_{\mathcal{M}}) / (kc_s))^{1/s} = \mathcal{O}(k^{-1/s})$$

r -packing is a $2r$ -covering:

$$\max_{i=1,\dots,n} \|\mathbf{x}_i - \mathbf{c}\|_2 \leq Rm/(m-1) \leq 2(1+\varepsilon)\mathcal{O}(k^{-1/s}) = \mathcal{O}(k^{-1/s})$$

But what about $\|\mathbf{L}^q - \mathbf{L}^o\|_F$?

Online SSL with Graphs: Analysis

Bounding **quantization error** $(\ell_t^q[t] - \ell_t^o[t])^2$

If similarity is M -Lipschitz, \mathbf{L} is normalized, $c_{ij}^o = \sqrt{\mathbf{D}_{ii}^o \mathbf{D}_{jj}^o} > c_{\min} n$:

$$\begin{aligned}\mathbf{L}_{ij}^q - \mathbf{L}_{ij}^o &= \frac{\mathbf{W}_{ij}^q}{c_{ij}^q} - \frac{\mathbf{W}_{ij}^o}{c_{ij}^o} \\ &\leq \frac{\mathbf{W}_{ij}^q - \mathbf{W}_{ij}^o}{c_{ij}^q} + \frac{\mathbf{W}_{ij}^q (c_{ij}^q - c_{ij}^o)}{c_{ij}^o c_{ij}^q} \\ &\leq \frac{4MRm}{(m-1)c_{\min}n} + \frac{4M(nMRm)}{((m-1)c_{\min}n)^2} \\ &= O\left(\frac{R}{n}\right)\end{aligned}$$

Finally, $\|\mathbf{L}^q - \mathbf{L}^o\|_F^2 \leq n^2 \mathcal{O}(R^2/n^2) = \mathcal{O}(k^{-2/s})$.

Are the assumptions reasonable?

Online SSL with Graphs: Analysis

Bounding **quantization error** $(\ell_t^q[t] - \ell_t^o[t])^2$

We showed $\|\mathbf{L}^q - \mathbf{L}^o\|_F^2 \leq n^2 \mathcal{O}(R^2/n^2) = \mathcal{O}(k^{-2/s}) = \mathcal{O}(1)$.

$$\frac{1}{n} \sum_{t=1}^n (\ell_t^q[t] - \ell_t^o[t])^2 \leq \frac{n_I}{c_u^2 \gamma_g^4} \|\mathbf{L}^q - \mathbf{L}^o\|_F^2 \leq \frac{n_I}{c_u^2 \gamma_g^4}$$

This converges to zero at the rate of $\mathcal{O}(n^{-1/2})$ with $\gamma_g = \Omega(n^{1/8})$.

With properly setting γ_g , e.g., $\gamma_g = \Omega(n^{1/8})$, we can have:

$$\frac{1}{n} \sum_{t=1}^n (\ell_t^q[t] - y_t)^2 = \mathcal{O}(n^{-1/2})$$

What does that mean?

SSL with Graphs: What is behind it?

Why and when it helps?

Can we guarantee benefit of SSL over SL?

Are there cases when **manifold** SSL is provably helpful?

Say \mathcal{X} is supported on manifold \mathcal{M} . Compare two cases:

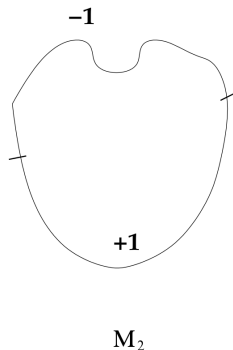
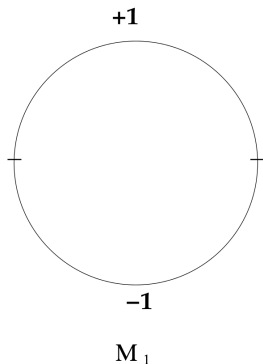
- ▶ SL: does not know about \mathcal{M} and only knows (\mathbf{x}_i, y_i)
- ▶ SSL: perfect knowledge of $\mathcal{M} \equiv$ humongous amounts of \mathbf{x}_i

<http://people.cs.uchicago.edu/~niyogi/papersps/ssminimax2.pdf>

SSL with Graphs: What is behind it?

Set of learning problems - collections \mathcal{P} of probability distributions:

$$\mathcal{P} = \cup_{\mathcal{M}} \mathcal{P}_{\mathcal{M}} = \cup_{\mathcal{M}} \{p \in \mathcal{P} | p_{\mathcal{X}} \text{ is uniform on } \mathcal{M}\}$$



SSL with Graphs: What is behind it?

Set of problems $\mathcal{P} = \cup_{\mathcal{M}} \mathcal{P}_{\mathcal{M}} = \{p \in \mathcal{P} | p_{\mathcal{X}} \text{ is uniform on } \mathcal{M}\}$

Regression function $m_p = \mathbb{E}[y | x]$ when $x \in \mathcal{M}$

Algorithm A and **labeled examples** $\bar{z} = \{z_i\}_{i=1}^n = \{(\mathbf{x}_i, y_i)\}_{i=1}^n$

Minimax rate

$$R(n, \mathcal{P}) = \inf_A \sup_{p \in \mathcal{P}} \mathbb{E}_{\bar{z}} [\|A(\bar{z}) - m_p\|_{L^2(p_{\mathbf{X}})}]$$

Since $\mathcal{P} = \cup_{\mathcal{M}} \mathcal{P}_{\mathcal{M}}$

$$R(n, \mathcal{P}) = \inf_A \sup_{\mathcal{M}} \sup_{p \in \mathcal{P}_{\mathcal{M}}} \mathbb{E}_{\bar{z}} [\|A(\bar{z}) - m_p\|_{L^2(p_{\mathbf{X}})}]$$

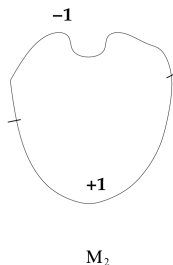
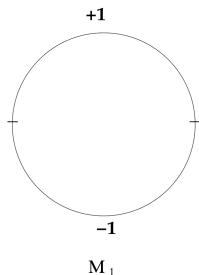
(SSL) When A is allowed to know \mathcal{M}

$$Q(n, \mathcal{P}) = \sup_{\mathcal{M}} \inf_A \sup_{p \in \mathcal{P}_{\mathcal{M}}} \mathbb{E}_{\bar{z}} [\|A(\bar{z}) - m_p\|_{L^2(p_{\mathbf{X}})}]$$

In which cases there is a gap between $Q(n, \mathcal{P})$ and $R(n, \mathcal{P})$?

SSL with Graphs: What is behind it?

Hypothesis space \mathcal{H} : half of the circle as $+1$ and the rest as -1



Case 1: \mathcal{M} is known to the learner ($\mathcal{H}_{\mathcal{M}}$)

What is a VC dimension of $\mathcal{H}_{\mathcal{M}}$?

$$\text{Optimal rate } Q(n, \mathcal{P}) \leq 2\sqrt{\frac{3 \log n}{n}}$$

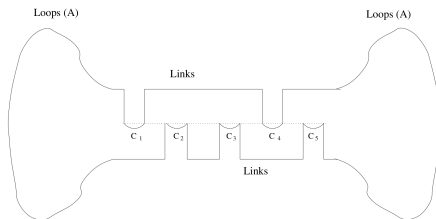
SSL with Graphs: What is behind it?

Case 2: \mathcal{M} is **unknown** to the learner

$$R(n, \mathcal{P}) = \inf_A \sup_{p \in \mathcal{P}} \mathbb{E}_{\bar{z}} [\|A(\bar{z}) - m_p\|_{L^2(p_{\mathbf{X}})}] = \Omega(1)$$

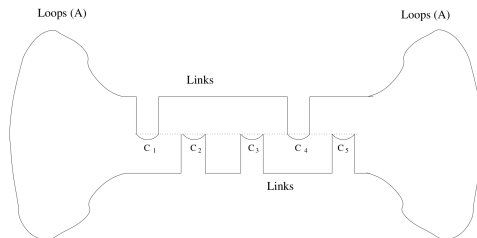
We consider 2^d manifolds of the form

$$\mathcal{M} = \text{Loops} \cup \text{Links} \cup C \text{ where } C = \cup_{i=1}^d C_i$$



Main idea: d segments in C , $d - l$ with no data, 2^l possible choices for labels, which helps us to lower bound $\|A(\bar{z}) - m_p\|_{L^2(p_{\mathbf{X}})}$

SSL with Graphs: What is behind it?



Knowing the manifold helps

- ▶ C_1 and C_4 are close
- ▶ C_1 and C_3 are far
- ▶ we also need: **target function varies smoothly**
- ▶ altogether: **closeness on manifold** → **similarity in labels**

SSL with Graphs: What is behind it?

What does it mean to **know** \mathcal{M} ?

Different degrees of knowing \mathcal{M}

- ▶ set membership oracle: $\mathbf{x} \stackrel{?}{\in} \mathcal{M}$
- ▶ approximate oracle
- ▶ knowing the harmonic functions on \mathcal{M}
- ▶ knowing the Laplacian $\mathcal{L}_{\mathcal{M}}$
- ▶ knowing eigenvalues and *eigenfunctions*
- ▶ topological invariants, e.g., dimension
- ▶ metric information: geodesic distance

Scaling SSL with Graphs to Millions

Semi-supervised learning with graphs

$$\mathbf{f}^* = \min_{\mathbf{f} \in \mathbb{R}^n} (\mathbf{f} - \mathbf{y})^T \mathbf{C} (\mathbf{f} - \mathbf{y}) + \mathbf{f}^T \mathbf{L} \mathbf{f}$$

Let us see the same in eigenbasis of $\mathbf{L} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T$, i.e., $\mathbf{f} = \mathbf{U} \boldsymbol{\alpha}$

$$\boldsymbol{\alpha}^* = \min_{\boldsymbol{\alpha} \in \mathbb{R}^n} (\mathbf{U} \boldsymbol{\alpha} - \mathbf{y})^T \mathbf{C} (\mathbf{U} \boldsymbol{\alpha} - \mathbf{y}) + \boldsymbol{\alpha}^T \mathbf{\Lambda} \boldsymbol{\alpha}$$

What is the problem with scalability?

Diagonalization of $n \times n$ matrix

What can we do? Let's take only first k eigenvectors $\mathbf{f} = \mathbf{U} \boldsymbol{\alpha}$!

Scaling SSL with Graphs to Millions

\mathbf{U} is now a $n \times k$ matrix

$$\alpha^* = \min_{\alpha \in \mathbb{R}^n} (\mathbf{U}\alpha - \mathbf{y})^T \mathbf{C}(\mathbf{U}\alpha - \mathbf{y}) + \alpha^T \mathbf{\Lambda} \alpha$$

Closed form solution is $(\mathbf{\Lambda} + \mathbf{U}^T \mathbf{C} \mathbf{U})\alpha = \mathbf{U}^T \mathbf{C} \mathbf{y}$

What is the size of this system of equation now?

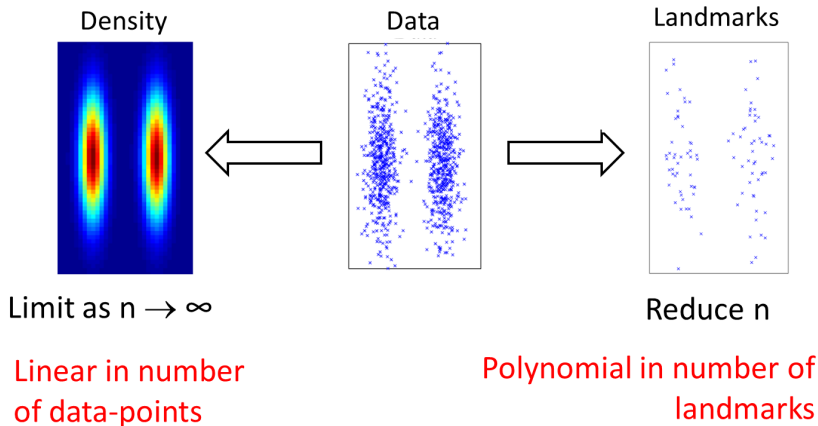
Cool!

Any problem with this approach?

Are there any reasonable assumptions when this is feasible?

Let's see what happens when $n \rightarrow \infty$!

Scaling SSL with Graphs to Millions



https://cs.nyu.edu/~fergus/papers/fwt_ssl.pdf

Scaling SSL with Graphs to Millions

What happens to \mathbf{L} when $n \rightarrow \infty$?

We have data $\mathbf{x}_i \in \mathbb{R}$ sampled from $p(\mathbf{x})$.

When $n \rightarrow \infty$, instead of vectors \mathbf{f} , we consider functions $F(x)$.

Instead of \mathbf{L} , we define \mathcal{L}_p - **weighted smoothness operator**

$$\mathcal{L}_p(F) = \frac{1}{2} \int (F(\mathbf{x}_1) - F(\mathbf{x}_2))^2 W(\mathbf{x}_1, \mathbf{x}_2) p(\mathbf{x}_1) p(\mathbf{x}_2) d\mathbf{x}_1 d\mathbf{x}_2$$

$$\text{with } W(\mathbf{x}_1, \mathbf{x}_2) = \frac{\exp(-\|\mathbf{x}_1 - \mathbf{x}_2\|^2)}{2\sigma^2}$$

\mathbf{L} defined the eigenvectors of increasing smoothness.

What defines \mathcal{L}_p ? **Eigenfunctions!**

Scaling SSL with Graphs to Millions

$$\mathcal{L}_p(F) = \frac{1}{2} \int (F(\mathbf{x}_1) - F(\mathbf{x}_2))^2 W(\mathbf{x}_1, \mathbf{x}_2) p(\mathbf{x}_1) p(\mathbf{x}_2) d\mathbf{x}_1 d\mathbf{x}_2$$

First eigenfunction

$$\Phi_1 = \arg \min_{F: \int F^2(\mathbf{x}) p(\mathbf{x}) D(\mathbf{x}) d\mathbf{x} = 1} \mathcal{L}_p(F)$$

where $D(\mathbf{x}) = \int_{\mathbf{x}_2} W(\mathbf{x}, \mathbf{x}_2) p(\mathbf{x}_2) d\mathbf{x}_2$

What is the solution? $\Phi_1(\mathbf{x}) = 1$ because $\mathcal{L}_p(1) = 0$

How to define Φ_2 ? Same, constraining to be orthogonal to Φ_1

$$\int F(\mathbf{x}) \Phi_1(\mathbf{x}) p(\mathbf{x}) D(\mathbf{x}) d\mathbf{x} = 0$$

Scaling SSL with Graphs to Millions

Eigenfunctions of \mathcal{L}_p

Φ_3 as before, orthogonal to Φ_1 and Φ_2 etc.

How to define eigenvalues? $\lambda_k = \mathcal{L}_p(\Phi_k)$

Relationship to the discrete Laplacian

$$\frac{1}{n^2} \mathbf{f}^\top \mathbf{L} \mathbf{f} = \frac{1}{2n^2} \sum_{ij} W_{ij} (f_i - f_j)^2 \xrightarrow{n \rightarrow \infty} \mathcal{L}_p(F)$$

http://www.informatik.uni-hamburg.de/ML/contents/people/luxburg/publications/Luxburg04_diss.pdf

<http://arxiv.org/pdf/1510.08110v1.pdf>

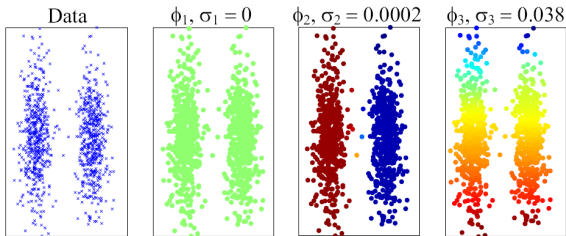
Isn't estimating eigenfunctions $p(\mathbf{x})$ more difficult?

Are there some "easy" distributions?

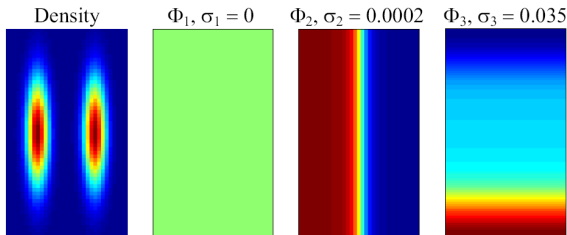
Can we compute it numerically?

Scaling SSL with Graphs to Millions

Eigenvectors



Eigenfunctions



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Factorized data distribution What if

$$p(\mathbf{s}) = p(s_1) p(s_2) \dots p(s_d)$$

In general, this is not true. But we can rotate data with $\mathbf{s} = \mathbf{R}\mathbf{x}$.



Treating each factor individually

$p_k \stackrel{\text{def}}{=} \text{marginal distribution of } s_k$

$\Phi_i(s_k) \stackrel{\text{def}}{=} \text{eigenfunction of } \mathcal{L}_{p_k} \text{ with eigenvalue } \lambda_i$

Then: $\Phi_i(\mathbf{s}) = \Phi_i(s_k)$ is eigenfunction of \mathcal{L}_p with λ_i

We only considered single-coordinate eigenfunctions.

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How to approximate 1D density? Histograms!

Algorithm of Fergus et al. [FWT09] for eigenfunctions

- ▶ Find \mathbf{R} such that $\mathbf{s} = \mathbf{R}\mathbf{x}$
- ▶ For each “independent” s_k approximate $p(s_k)$
- ▶ Given $p(s_k)$ numerically solve for eigensystem of \mathcal{L}_{p_k}

$$\left(\tilde{\mathbf{D}} - \mathbf{P}\tilde{\mathbf{W}}\mathbf{P}\right)\mathbf{g} = \lambda\mathbf{P}\hat{\mathbf{D}}\mathbf{g} \quad (\text{generalized eigensystem})$$

\mathbf{g} - vector of length $B \equiv$ number of bins

\mathbf{P} - density at discrete points

$\tilde{\mathbf{D}}$ - diagonal sum of $\mathbf{P}\mathbf{W}\mathbf{P}$

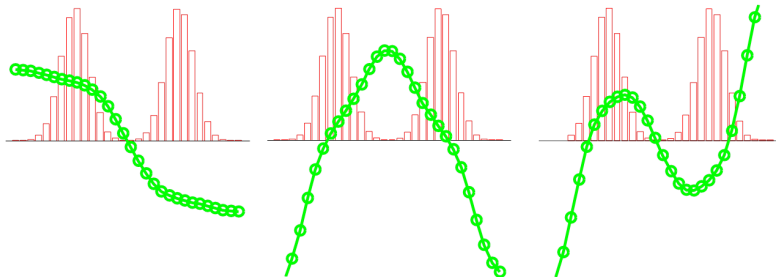
$\hat{\mathbf{D}}$ - diagonal sum of $\mathbf{P}\tilde{\mathbf{W}}$

- ▶ Order eigenfunctions by increasing eigenvalues

https://cs.nyu.edu/~fergus/papers/fwt_ssl.pdf

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Numerical 1D Eigenfunctions



1st Eigenfunction
of $h(x_1)$

2nd Eigenfunction
of $h(x_1)$

3rd Eigenfunction
of $h(x_1)$

https://cs.nyu.edu/~fergus/papers/fwt_ssl.pdf

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Computational complexity for $n \times d$ dataset

Typical harmonic approach

one diagonalization of $n \times n$ system

Numerical eigenfunctions with B bins and k eigenvectors

d eigenvector problems of $B \times B$

$$\left(\tilde{\mathbf{D}} - \mathbf{P}\tilde{\mathbf{W}}\mathbf{P} \right) \mathbf{g} = \lambda \mathbf{P}\hat{\mathbf{D}}\mathbf{g}$$

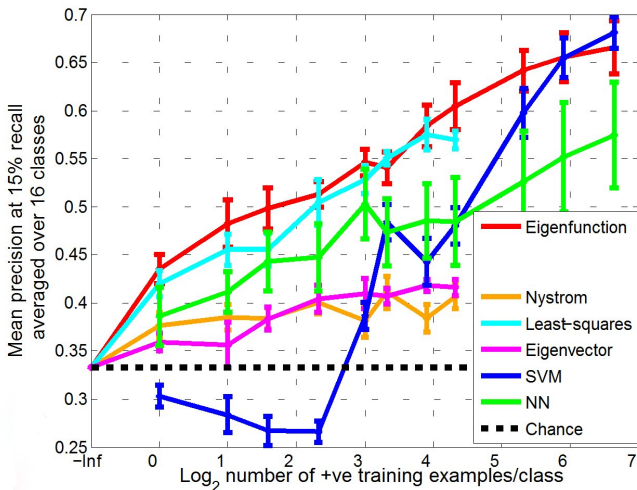
one $k \times k$ least squares problem

$$(\mathbf{\Lambda} + \mathbf{U}^T \mathbf{C} \mathbf{U}) \alpha = \mathbf{U}^T \mathbf{C} \mathbf{y}$$

some details: several approximation, eigenvectors only linear combinations single-coordinate eigenvectors, ...

When d is not too big then n can be in millions!

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CIFAR experiments https://cs.nyu.edu/~fergus/papers/fwt_ssl.pdf

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