



Graphs in Machine Learning

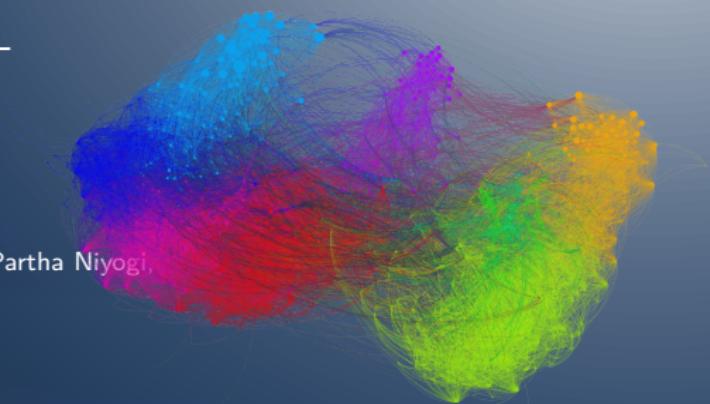
Transductive Generalization Bounds

Stability-Based Bounds for SSL

Michal Valko

Inria & ENS Paris-Saclay, MVA

Partially based on material by: Mikhail Belkin, Partha Niyogi,
Olivier Chapelle, Bernhard Schölkopf



Transductive Generalization Bounds

True risk vs. empirical risk

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$$R_P(f) = \frac{1}{N} \sum_i (f_i - y_i)^2$$
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We look for **transductive** bounds in the form

$$R_P(f) \leq \hat{R}_P(f) + \text{errors}$$

Transductive Generalization Bounds

Bounding transductive error using stability analysis

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$$\ell^* = \min_{\ell \in \mathbb{R}^N} (\ell - \mathbf{y})^\top \mathbf{C} (\ell - \mathbf{y}) + \ell^\top \mathbf{Q} \ell$$

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Closed form solution

$$\ell^* = (\mathbf{C}^{-1} \mathbf{Q} + \mathbf{I})^{-1} \mathbf{y}$$

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By the generalization bound of Belkin Belkin et al., 2004,
w.p.1 - δ

http://web.cse.ohio-state.edu/~mbelkin/papers/RSS_COLT_04.pdf

$$R_P(\ell^*) \leq \widehat{R}_P(\ell^*) + \underbrace{\beta + \sqrt{\frac{2 \ln(2/\delta)}{n_I} (n_I \beta + 4)}}_{\text{transductive error } \Delta_T(\beta, n_I, \delta)}.$$

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Bounding transductive error

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$$\beta \leq 2 \left[\frac{\sqrt{2}}{\gamma_g + 1} + \sqrt{2n_l} \frac{1 - c_u}{c_u} \frac{\lambda_M(\mathbf{L}) + \gamma_g}{\gamma_g^2 + 1} \right]$$

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This algorithm is β -stable!

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We have an idea how to set γ_g !

Michal Valko

`michal.valko@inria.fr`

Inria & ENS Paris-Saclay, MVA



`https://misovalko.github.io/mva-ml-graphs.html`