

Graphs in Machine LearningSpectral Graph Sparsifiers: Theory

Effective Resistance and Spielman-Teng Algorithm

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Partially based on material by: Rob Fergus, Nikhil Srivastav Yiannis Koutis, Joshua Batson, Daniel Spielman

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As a consequence, $\arg\min_{\mathbf{x}} \|\mathbf{L}_H\mathbf{x} - \mathbf{b}\| \approx \arg\min_{\mathbf{x}} \|\mathbf{L}_G\mathbf{x} - \mathbf{b}\|$

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- in $\mathcal{O}(m\log^2(n))$ time and $\mathcal{O}(n\log(n)/\varepsilon^2)$ space
- a single pass over the data

Laplacian smoothing (denoising): given $\mathbf{y} \triangleq \mathbf{f}^* + \xi$ and G compute

$$\min_{\mathbf{f} \in \mathbb{R}^n} (\mathbf{f} - \mathbf{y})^\mathsf{T} (\mathbf{f} - \mathbf{y}) + \lambda \mathbf{f}^\mathsf{T} \mathbf{L}_G \mathbf{f}$$
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Preproc Time Space
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Large computational improvement

→ accuracy guarantees! [sadhanala2016graph]

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Need to approximate spectrum only up to regularization level λ

Definition

An (ε, γ) -sparsifier of G is a reweighted subgraph H s.t.

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Mixed multiplicative / additive error

- large (i.e. $\geq \gamma$) directions reconstructed accurately
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Adapted from Randomized Linear Algebra (RLA) community

L PSD matrix low-rank approx. [alaoui2014fast]

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RLA \to Graph: Improve over $\mathcal{O}(n \log n)$ exploiting regularization Graph \to RLA: Exploit \mathbf{L}_G structure for fast (ε, γ) -sparsification

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We look for a subgraph H

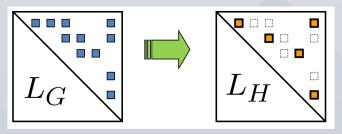
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$$\mathbf{L}_H = \sum_{e \in E} s_e \mathbf{b}_e \mathbf{b}_e^{\mathsf{T}}$$
 where s_e is a new weight of edge e



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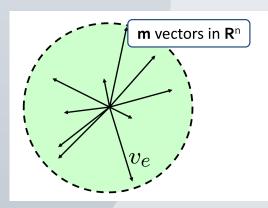
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Then
$$\sum_{e \in E} s_e \mathbf{v}_e \mathbf{v}_e^{\mathsf{T}} \approx \mathbf{I} \iff \sum_{e \in E} s_e \mathbf{a}_e \mathbf{a}_e^{\mathsf{T}} \approx \mathbf{A}$$

multiplying by $A^{1/2}$ on both sides

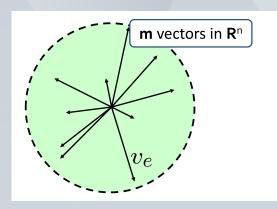
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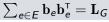
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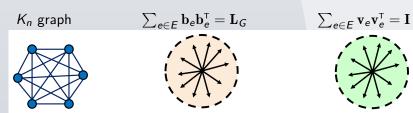








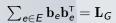
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It is already isotropic! (looks like a sphere)

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rescaling $\mathbf{v}_{e} = \mathbf{L}^{-1/2}\mathbf{b}_{e}$ does not change the shape

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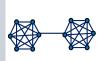
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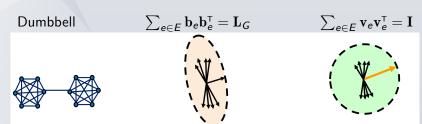
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The vector corresponding to the link gets stretched!

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Dumbbell

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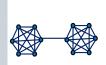
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$$\sum_{e \in F} \mathbf{v}_e \mathbf{v}_e^{\mathsf{T}} = \mathbf{I}$$







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because this transformation makes all the directions important

rescaling reveals the vectors that are critica

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https://misovalko.github.io/mva-ml-graphs.html